

SYSTEM AND METHOD FOR MONITORING GROUPED RESOURCES

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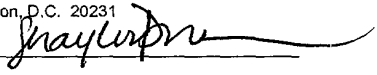
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Description

SYSTEM AND METHOD FOR MONITORING GROUPED RESOURCES

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Technical Field

The present invention relates generally to systems and methods for indicating resource quantity in document processing systems. More particularly, the present invention relates to a system and method for indicating the quantity of a group of sheets or inserts stored in a hopper for processing by a mail insertion machine.

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Background Art

Mail insertion machines automatically associate together, process, and place sheet articles (e.g., one or more papers, documents, or envelopes) into envelopes for mass mailing. Thereafter, a mail insertion machine can perform various other operations, such as sealing an envelope, associating stuffed envelopes with an appropriate postage weight category, and grouping or sorting by zip code or in accordance with other criteria. Mail insertion machines typically include a track to move mail pieces along an assembly line for sequential processing by one or more insert stations. Each insert station typically includes one or more hoppers, or containers, for storing sheet articles in a stack until required for processing. A single cycle of operation by an insert station usually includes removing one sheet article from the hopper via a mechanical device

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and subsequently stuffing the sheet article into an envelope, folding it, marking it, or otherwise preparing it for mailing.

Current mail insertion machines include a sensor to detect a low stack condition and a system for alerting an operator to a low stack condition. It is possible in mail processing for an operator to fail to replenish the sheet article stack despite receiving a low stack condition warning. Such a failure to replenish the sheet article supply can result in an unnecessary and undesirable delay in processing. Additionally, in many known insert stations, sheet articles will fall from the sheet article stack onto the track once the sheet article stack size, or level, is less a certain size.

One known approach for alleviating these problems is to provide a first sensor for detecting when the quantity of sheet articles is below a first measured size and a second sensor for detecting when the quantity of sheet articles is below a second measured size. When the quantity is depleted until it is below the first measured size, an alert is activated to signal a low stack condition. When the quantity is depleted below the second measured size, an alert is activated to indicate the low stack condition and the insert station can be halted from pulling any more sheet articles from the stack. A disadvantage of this solution is the requirement of two sensors, thus increasing the cost of the machine.

Therefore, it is desired to improve the indication of a low stack condition. It is also desired to indicate to an operator that a sheet article stack height has fallen below a predetermined size. Furthermore, it is desired to halt the processing of any more sheet articles once the hopper has reached a second measured size without the use of a second sensor.

Disclosure of the Invention

According to one embodiment, a method of monitoring resource units in a stack is provided. The method includes providing a group of resource units and determining a thickness of one or more of the resource units. The method also
5 includes indicating when the group of resource units reaches a predetermined size after one or more of the resource units has been moved from the group.

According to a second embodiment, a method of monitoring resource units in a group of resource units is provided. The method includes detecting a size of resource units in a group of resource units. The method also includes
10 calculating, based upon the thicknesses of at least one of the resource units, when the group of resource units reaches a predetermined size after one or more resource units has been moved from the group.

According to a third embodiment, a method for controlling removal of sheet articles from a stack is provided. The method includes detecting a level of
15 a stack of sheet articles and removing one or more sheet articles from the stack. Furthermore, the method includes determining a thickness of at least one of the sheet articles removed from the stack and indicating when the stack of sheet articles reaches a predetermined level. Still furthermore, the method includes stopping removal of sheet articles from the stack.

20 According to a fourth embodiment, a system for monitoring resource units in a stack is provided. The system includes a container for containing a group of resource units. The system also includes a device for determining a thickness of one or more of the resource units. Furthermore, the system includes an indicator for indicating when the group of resource units reaches a predetermined size
25 after one or more of the resource units has been moved from the group.

According to a fifth embodiment, a system for monitoring resource units in a group of resource units is provided. The system includes a measurement detector for detecting a size of resource units in a group of resource units. Furthermore, the system includes a controller for calculating, based upon the thickness of at least one of the resource units, when the group of resource units reaches a predetermined size after one or more resource units has been moved from the group.

According to a sixth embodiment, a system for controlling removal of sheet articles from a stack is provided. The system includes a measurement detector for detecting a level of a stack of sheet articles. The system also includes a mechanical device for removing one or more sheet articles from the stack. Furthermore, the system includes a means for determining a thickness of at least one of the sheet articles removed from the stack. Still furthermore, the system includes an indicator for indicating when the stack of sheet articles reaches a predetermined level and selectively stopping removal of sheet articles from the stack.

According to a seventh embodiment, a computer program product for monitoring resource units in a stack is provided. The computer program product comprising computer-executable instructions embodied in a computer-readable medium for performing steps. The steps include detecting a size of resource units in a group of resource units. Furthermore, the steps include calculating, based upon the thicknesses of at least one of the resource units, when the group of resource units reaches a predetermined size after one or more resource units has been moved from the group.

Accordingly, it is an object to provide a novel system and method for the detection and processing of grouped resource units, particularly for stack documents such as inserts for mail processing.

Some of the objects having been stated and which are achieved in whole
5 or in part, other objects will become evident as the description proceeds when taken in connection with the accompanying drawings as best described hereinbelow.

Brief Description of the Drawings

10 Exemplary embodiments of the invention will now be explained with reference to the accompanying drawings, of which:

Figure 1 is a schematic diagram of a mail insertion system according to a preferred embodiment;

Figure 2 is a schematic diagram of a cross-sectional view of an exemplary
15 hopper according an embodiment, wherein the insert stack is above a predetermined level;

Figure 3 is a schematic diagram of a cross-sectional view of an exemplary hopper according to an embodiment, wherein the insert stack is below a predetermined level and above a minimum level;

20 Figure 4 is a schematic diagram of a cross-sectional view of an exemplary hopper according to an embodiment, wherein the insert stack is equal to a minimum level;

Figure 5 is a schematic diagram of a display screen indicating a low stack condition;

Figure 6 is a schematic diagram of a display screen indicating a stack condition above a predetermined level; and

Figure 7 is a diagram of a gripper arm for removing sheet articles one or more at a time from a sheet article stack in a hopper; and

5 Figure 8 is a flow chart illustrating a process for resource management in a machine according to one embodiment.

Detailed Description of the Invention

10 The invention now is described more fully hereinafter with reference to the accompanying drawings, in which preferred embodiments of the invention are shown. This invention can, however, be embodied in many different forms and should not be construed as limited to the embodiments set forth herein; rather, these embodiments are provided so that this disclosure will be thorough and complete, and will fully convey the scope of the invention to those skilled in the
15 art.

As will be appreciated by one of skill in the art, the present invention can be embodied as a method, system, or computer program product. Accordingly, the present invention can take the form of an entirely hardware embodiment, an entirely software embodiment, or an embodiment combining software and
20 hardware aspects. Furthermore, the present invention can take the form of a computer program product on a computer-readable storage medium having computer-readable program code means embodied in the medium. Any suitable computer readable medium can be utilized including hard disks, CD-ROMs, optical storage devices, or magnetic storage devices.

The invention is described below with reference to flowchart illustrations of methods, apparatus (systems), and computer program products according to the invention. It will be understood that each block of the flowchart illustrations, and combinations of blocks in the flowchart illustrations, can be implemented by

5 computer program instructions. These computer program instructions can be loaded onto a general purpose computer, special purpose computer, or other programmable data processing apparatus to produce a machine, such that the instructions which execute on the computer or other programmable data processing apparatus create means for implementing the functions specified in

10 the flowchart block or blocks. These computer program instructions can also be stored in a computer-readable memory that can direct a computer or other programmable data processing apparatus to function in a particular manner, such that the instructions stored in the computer-readable memory produce an article of manufacture including instruction means which implement the function

15 specified in the flowchart block or blocks. The computer program instructions can also be loaded onto a computer or other programmable data processing apparatus to cause a series of operational steps to be performed on the computer or other programmable apparatus to produce a computer implemented process such that the instructions which execute on the computer or other

20 programmable apparatus provide steps for implementing the functions specified in the flowchart block or blocks.

Accordingly, blocks of the flowchart illustrations support combinations of means for performing the specified functions, combinations of steps for performing the specified functions and program instruction means for performing

25 the specified functions. It will also be understood that each block of the flowchart

illustrations, and combinations of blocks in the flowchart illustrations, can be implemented by special purpose hardware-based computer systems which perform the specified functions or steps, or combinations of special purpose hardware and computer instructions.

5 As will readily be appreciated by those of skill in the art, the inventive apparatus and methods can be applied to several types of machines requiring the indication of the size of a group of resource units. As described herein, the disclosed apparatus and methods can be applied to mail insertion machines for the indication of the quantity of a sheet article stack with respect to a
10 measurement. Furthermore, the disclosed apparatus and methods can be applied to copiers, printers, and facsimile machines requiring resource unit monitoring and other such machines requiring resource size indication. Additionally, the disclosed apparatus and methods can be applied to machines requiring other size indication such as an indication of the supply of toner.

15 The disclosed apparatus and methods are described with regard to sheet articles in a mail insertion machine. As will readily be appreciated by those of skill in the art, the disclosed apparatus and methods can be applied to several types of sheet articles that are collected in a group and moved from the group one or more at a time.

20 Referring to FIG. 1, a schematic diagram of a mail insertion system **100** according to a preferred embodiment is illustrated. Mail insertion system **100** includes a controller **102** for operating and transmitting information to and receiving information from a touch screen display **104** and a sensor **106**. Additionally, controller **102** can be used for operating and monitoring various
25 other components of the mail insertion system **100**. Display **104**, described in

more detail below, visually displays information to an operator and allows the operator to provide input to the mail insertion system **100**. Sensor **106**, described in more detail below, indicates whether the quantity of inserts stored in a primary hopper **108** is below a certain measurement. As referred to herein, a sheet article is a single resource unit among several resource units, or sheet articles, stored in primary hopper **108**. As described in more detail below, the present invention can be stored in the components of controller **102**, either within internal memory or on internal disk storage. The present invention can also be stored on computer readable media.

Controller **102** includes a measurement detector **110** operatively connected to sensor **106** (by or through a cable or another signal transmission device known to those of skill in the art) for detecting whether the level of a group of sheet articles in primary hopper **108** of an insert station **112** is below the measurement indicated by sensor **106**. Controller **102** also includes a counter **114** for counting the number of sheet articles moved from primary hopper **108** while the level of the group of sheet articles is below the measurement indicated by measurement detector **110**. When the number of sheet articles moved from primary hopper **108** is equal to a predetermined number, display **104** functions as an indicator for indicating that the level is equal to or less than a second measurement. The functions of measurement detector **110**, counter **114**, and display **104** in a measurement of the level of the group of sheet articles in primary hopper **108** will be described in further detail below.

In a preferred embodiment, controller **102** controls the operation of a gripper arm (not shown) for removing sheet articles one or more at a time from the sheet article stack in primary hopper **108**. The gripper arm pulls sheet

articles from the bottom of the sheet article stack. In this embodiment, the gripper arm also measures the thickness of the sheet article and transmits this information to controller **102** as sheet articles are pulled from the stack. When controller **102** detects that five sheet articles have been pulled in a row with the same thickness, the measured thickness of the sheet article is calibrated as the measure of the thickness of these sheet articles. Controller **102** provides counter **114** indication of the removal of a sheet article from primary hopper **108**. Other suitable means for removing a sheet article from the sheet article stack as known to those of skill in the art can be used.

Other than primary hopper **108**, mail insertion system **100** in a preferred embodiment includes five hoppers (other than primary hopper **108**) including a backup hopper **116** functioning as a backup to primary hopper **108**. Sheet articles can be pulled from backup hopper **116** in the case of a sheet article shortage, hopper fault, or otherwise as described below. In this embodiment, backup hopper **116** stores sheet articles identical to those sheet articles in primary hopper **108**. While the four hoppers in addition to primary hopper **108** and backup hopper **116** are not shown in FIG. 1, it is envisioned that any suitable number of backup hoppers could be utilized.

A method for indicating the level of a group of sheet articles in a mail insertion machine includes detecting whether the level of the group of sheet articles is below a predetermined level. In the embodiment shown in FIG. 1, resource detection can be performed by measurement detector **110**. Measurement detector **110** receives input from sensor **106** for detecting whether the level of the group of sheet articles is below a predetermined level.

Furthermore, measurement detector **110** indicates to counter **114** when the level of the sheet article group is below the measurement by sensor **106**.

Referring to FIGs. 2-4, schematic diagrams are illustrated of a cross-sectional view of an exemplary hopper, generally designated **108**, having sensor **106** for detecting a top level **200** of a sheet article stack **202**. FIGs. 2-4 show top level **200** at various heights with respect to a measured level **204** and a predetermined level **206**. Measured level **204** is determined by sensor **106**. Predetermined level **206** is the measured quantity of sheet article stack **202** as determined by controller **102** provided with measured level **204** and an indication of the removal of sheet articles. Hopper **108** includes adjustable opposing sides **208** and **210** for providing side support to sheet article stack **202**. Sheet articles within sheet article stack **202** rests flat against one another on a base **212** of hopper **108**. Sheet articles are stacked in a direction **x 214**.

Referring now specifically to FIG. 2, the exemplary schematic diagram illustrates sheet article stack **202** wherein top level **200** is above measured level **204**. The thickness of a single insert is approximately a distance **a 216** in a direction **x 214**. Level **200** is reduced a distance equal to distance **a 216** each time a cycle is run by insert station **112** requiring a sheet article from primary hopper **108**.

Sensor **106** is mounted on primary hopper **108** a distance from base **212** for detecting that top level **200** is either above or below the distance. In this embodiment, sensor **106** is a switch type sensor. Sensor **106** is activated to indicate that top level **200** is above measured level **204** when sheet article stack **202** presses against sensor **106**. As shown in FIG. 2, top level **200** is above sensor **106**. Thus, measurement detector **110** detects that top level **200** is above

measured level **204**. Once enough inserts are pulled from sheet article stack **202** so that level **200** is below measured level **204**, sensor **106** is de-activated and measurement detector **110** detects that level **200** is below measured level **204**.

Referring now to FIG. 3, the exemplary schematic diagram illustrates
5 sheet article stack **202** wherein level **200** is below measured level **204** and above predetermined level **206**. As described in more detail below, when level **200** is between measured level **204** and predetermined level **206**, the operator is alerted to a low stack condition via display **104**.

Referring now to FIG. 4, the exemplary schematic diagram illustrates
10 sheet article stack **202** wherein level **200** is equal to predetermined level **206**. Predetermined level **206** is below measured level **204** a distance **b 218**. Predetermined level **206** is above base **212** a distance **c 220**. As described in more detail below, when level **200** is equal to predetermined level **206**, the operator is alerted to another low stack condition via display **104**. The disclosed
15 apparatus and methods can be used to determine when level **200** has been reduced to a quantity approximately equal to predetermined level **206** as described in further detail below.

As discussed above, sensor **106** in this embodiment is a switch type sensor. Alternatively, a retro-reflective optical sensor can be used, as well as
20 other suitable sensors known to those of skill in the art.

A method for indicating the level of a group of sheet articles in a mail insertion machine includes counting the number of sheet articles moved from the group of sheet articles while the level is below the sensor measurement. Such counting can be performed by counter **114**. Counter **114** receives input from
25 measurement detector **110** for counting the number of sheet articles removed

from sheet article stack **202** when level **200** is below measured level **204**, as shown and described with regard to FIGs. 2-4.

Counter **114** provides an indication when level **200** is equal to predetermined level **206**. In this embodiment, when this occurs insert station **112** is disabled from pulling sheet articles from primary hopper **108**, and insert station **112** is enabled to pull sheet articles from backup hopper **116**. In an alternate embodiment without a backup hopper, the mail insertion system **100** can be disabled when this occurs. Furthermore, in another embodiment operator can be provided with an additional more urgent low stack condition warning.

Display **104** allows an operator to monitor and manage the operation of mail insertion system **100**. An operator is provided with the ability to turn on and off hoppers associated with insert stations via interaction with display **104**. Display **104** provides a visual indication of the operation of mail insertion system **100** to an operator. An operator can enter data via display **104** by depressing the display screen (not shown) at the appropriate space on its surface using a finger, pen, or other suitable device known to those of skill in the art.

Referring to FIG. 5, a schematic diagram of a display screen, generally designated **500**, indicating a low stack condition is illustrated. A low stack condition is indicated by low stack condition icon **502**. Icon **502** condition flashes on and off when the stack height or level **200** is between measured level **204** and predetermined level **206** to alert the operator to a low stack condition. When level **200** is equal to predetermined level **206** and lower, icon **502** remains on to alert operator to such an urgent low stack condition. A "six" number icon **504** positioned above the low stack condition icon **502** and an associated hopper

icon **506** indicates to the operator that these icons are associated with hopper number six.

Referring to FIG. 6, a schematic diagram of display screen, generally designated **500**, indicating a stack condition above measured level **204** is illustrated. This condition is indicated by the absence of low stack condition icon **502** (shown in FIG. 5).

Instead of a touch screen display, a conventional display, mouse, and keyboard can be used to allow an operator to provide input to the mail insertion system. With the mouse, the operator can move a pointer on the display to an area displaying an object. By pressing and releasing a button on the mouse while the pointer is in the area displaying the object or icon, the operator "activates" the icon for input. With the keyboard, the operator can enter commands to the mail insertion system. Alternatively, any other known suitable device for displaying or providing input to the mail insertion system as known to those of skill in the art can be used.

Referring to FIG. 7, a diagram of a conventional gripper arm, generally designated **800**, for removing sheet articles one or more at a time preferably from the bottom of a sheet article stack in a hopper is illustrated. An end **702** of gripper arm **700** is attached to and pivots on an axis **704**. An actuator (not shown) moves gripper arm **700** about axis **704**. a pivotable gripper jaw **706** is attached at an end **708** distal to end **702**. Opposite gripper jaw **706** is a gripper jaw **710** pivotally connected to an axis **712**. A rear extension **714** functions to move gripper jaw **710** about axis **712** via an actuator (not shown). Details of this mechanism are well known to those of skill in the art.

Attached to axis **712** is a lever **716** forming a movement transition-part. In the position shown in FIG. 7, lever **716** extends substantially in a direction along the length of gripper arm **700**. Thus, it is oriented in a predetermined angle of, e.g., 90 degrees with respect to the direction of the length of gripper jaw **710**. In operation, a sheet articles **718** can be engaged by gripper jaws **706** and **710**, sheet article **718** having been drawn off from the lower end of a stack. Sheet article **718**, by being interposed between gripper jaws **706** and **710**, causes a pivot position of gripper jaw **710**. The pivot position of gripper jaw **710** is detected by a detector **720** attached to gripper arm **700**. Detector **720** can be attached to controller **102** (shown in FIG. 1) via a line **722** for transmitting data indicating the pivot position of gripper jaw **710**. This data can be used by controller **102** for determining the thickness of sheet article **718** as well known to those of skill in the art. Alternatively, other suitable processes known to those of skill in the art can be used for determining the thickness of sheet articles.

Referring now to FIG. 8, a flow chart, generally designated **800**, is provided which illustrates a process for indicating the size or level of a group of sheet articles in a mail insertion machine according to a preferred embodiment of this invention. This indication of the level of the group of sheet articles can be performed by a computer system or controller, which can be local or remote. In this embodiment, sheet article level indication is performed by measurement detector **110** and counter **114** of controller **102** as shown in FIG. 1, and display **104** serving as a visual indication to the operator as shown in FIGs. 5 and 6. The process begins at the step indicated by reference numeral **802**.

In step **804**, controller **102** estimates the number of sheet articles that can be removed from hopper **108** until level **200** is equal to predetermined level **206**.

After determining when the level of the group of sheet articles is equal to the sensor measurement, the number of sheet articles required before reaching measured level **204** can be estimated if controller **102** is provided the following information: sheet article thickness (distance **a 216** shown in FIG. 2); and the
5 distance between measured level **204** and predetermined level **206** (distance **b 218** shown in FIG. 4). As referred to herein, cycle is a sequence run by an insert station **112** or any other component of mail insertion system **100** that depletes one sheet article from hopper **108**, thereby reducing level **200** a distance equal to the thickness of one sheet article. Therefore, provided the number of cycles
10 executed, the time when level **200** reaches predetermined level **206** can be determined. In this embodiment, sheet article thickness is calibrated by mail insertion system **100**. In one embodiment, the gripper arm can determine the thickness of the sheet article. In another embodiment, sheet article thickness can be provided to counter **114** through other suitable means known to those of skill
15 in the art.

The number of sheet articles removed to reduce the sheet article stack height a distance can be determined by the following equation, wherein C is the number of sheet articles, D is the distance the stack height is reduced, and T is the thickness of an sheet articles:

20
$$C = \frac{D}{T}$$

In this embodiment, the distance estimated is for a distance **b 218** (shown in FIG. 4), the distance separating measured level **204** and predetermined level **206**. Alternatively, the number of sheet articles, C , can be provided to counter **114** through other suitable means known to those of skill in the art, such as by
25 programming it into the system by an operator.

In step **806**, it is initially indicated to the operator that level **200** is above measured level **204** by the absence of low stack condition icon associated with the hopper. The absence of the low stack condition icon indicates to an operator that the sheet article supply in the stack is sufficient.

5 In step **808**, a determination is made as to whether level **200** is above measured level **204**. As stated above, measurement detector **110** can determine whether level **200** is above measured level **204**. If level **200** is above measured level **204**, the next step is step **806**, wherein it is indicated to the operator that level **200** is above measured level **204** by the absence of low stack condition
10 icon associated with the hopper. Otherwise, the operator is provided an indication of a low stack condition via the display of a low stack condition icon as described above (step **810**).

In step **812**, a determination is made as to whether level of the sheet articles has been below the predetermined level for the calculated number of
15 sheet articles for removal as described above. As described above, counter **114** determines whether the number of sheet articles removed is equal to the predetermined number of sheet articles for removal while the sheet article stack level is below the predetermined height. In this embodiment, if level **200** is below the measured level **204** before the removal of the predetermined number of
20 sheet articles, the next step is step **814**. Alternatively, it can then be determined that level **200** is above measured level **204**, and the next step is step **806**. If it is determined level **200** is below the measured level **204** for the removal of the predetermined number of sheet articles, the next step is step **816**, as described below.

In step **814**, a determination is made as to whether level **200** is above the predetermined stack height for a minimum amount of time. In this embodiment, the minimum amount of time is five seconds. This feature provides a safeguard to prevent an indication is above the measured level **204** if the sensor
5 erroneously detects such a condition. For example, the operator can add sheet articles to hopper **108**, and thus sensor **106** briefly detects the sheet articles as they are lowered past. This feature assures that the stack has been replenished and not just loaded to a level below measured level **204**. If level **200** is above the measured level **204** for the minimum amount of time, the next step is step **806** as
10 described above. Otherwise, the next step is step **816**, as described below.

In step **816**, insert station **112** is disabled from pulling sheet articles from hopper **108**. Thus, it is estimated that level **200** is approximately equal to predetermined level **206**. The operator is alerted via the display as described above (step **818**).

15 In step **820**, a determination is made as to whether there is a backup hopper for the primary hopper. If there is a backup hopper for the primary hopper, the backup hopper is enabled (step **822**), and then the flow process stops (step **824**). Otherwise, it is determined whether the "miss" feature is turned on (step **826**). A miss, as referred to herein, occurs when the gripper
20 arm fails to remove a sheet article, or "misses" a sheet article on an attempt to remove the sheet article.

If misses are turned on, the mail insertion system will fault after a predetermined number of fault cycles (step **828**), and the next step is step **824**. In this embodiment, the operator can set the number of fault cycles for execution

before fault to one to three cycles. If the misses are not turned on, the mail insertion system will continue to cycle, and the next step is step **824**.

The disclosed apparatus and methods can be implemented in a variety of communications environments including a Local Area Network (LAN) and Wide
5 Area Network (WAN) environments. The disclosed apparatus and methods can be implemented in communications environments utilizing TCP/IP communications protocol, such as the Internet, and environments utilizing SNA protocol. Hardware for implementing the disclosed apparatus and methods is generally consistent with typical personal computing equipment, and does not
10 generally require special environmental conditions other than a typical office environment. In one exemplary embodiment, the disclosed apparatus and methods can be implemented on an International Business Machines™ or IBM™-compatible personal computer and software capable of supporting a thin wire Ethernet TCP/IP environment. The server can be based on an Intel™
15 processor and having sufficient memory to perform all functions efficiently. In one embodiment, the printer is suitable for text and color graphical report printing; automatic back-up capability for data and configuration files; and trackball or mouse support. The disclosed apparatus and methods can be implemented via other computing device, including, but not limited to, mainframe
20 computing systems and mini-computers.

The disclosed methods can be written in various computer languages including, but not limited to, C++, Smalltalk, Java, and other conventional programming languages such as BASIC, FORTRAN, and COBOL.

Computer readable program code means is provided for receiving
25 processing system operation related information from each of a plurality of mail

insertion devices, and for representing each of the mail insertion devices as an interactive icon on a display connected to a data processing system. Each interactive icon has indicia associated therewith which displays the operation related information for a respective mail insertion device and changes appearance in response to a change in the operation related information. Computer readable program code means is provided for displaying selective operation related information about a respective mail insertion device in response to user actions, and for displaying operation related information for each mail insertion device in real time. Computer readable program code means is also provided for adding, deleting, and modifying the location and appearance of the interactive icons.

Certain inventive concepts involved here relate to a computer program product, for causing the processor serving as controller 102 to implement the group resource monitoring techniques described above. Such a computer program product comprises computer-executable instructions and/or associated data for causing a programmable processor to perform the sequence of operations involved in the resource monitoring. The computer-executable instructions are carried on or embodied in computer-readable medium.

The term "computer-readable medium" as used herein refers to any medium that participates in providing instructions to processor of the controller 102 for execution. Such a medium may take many forms, including but not limited to, non-volatile media, volatile media, and transmission media. Non-volatile media include, for example, optical or magnetic disks. Volatile media include dynamic memory, such as the main memory of a personal computer, a server or the like. Transmission media include coaxial cables; copper wire and

fiber optics, including the wires that for the bus within a computer. Transmission media can also take the form of electric or electromagnetic signals, or acoustic or light waves such as those generated during radio frequency (RF) and infrared (IR) data communications. Common forms of computer-readable media include, 5 for example, a floppy disk, a flexible disk, hard disk, magnetic tape, any other magnetic medium, a CD-ROM, DVD, any other optical medium, punch cards, paper tape, any other physical medium with patterns of holes, a RAM, a PROM, and EPROM, a FLASH-EPROM, any other memory chip or cartridge, a carrier wave transporting data or instructions, or any other medium from which a 10 computer can read. Various forms of computer readable media may be involved in carrying one or more sequences of one or more instructions to the processor for execution.

In alternative embodiments, hard-wired circuitry may be used in place of or in combination with software instructions to implement the invention. Thus, 15 embodiments of the invention are not limited to any specific combination of hardware circuitry and software.

It will be understood that various details of the invention can be changed without departing from the scope of the invention. Furthermore, the foregoing description is for the purpose of illustration only, and not for the purpose of 20 limitation--the invention being defined by the claims.